

MULTI-INJECT

3-AXIS ROBOTS FOR INJECTION MOLDING MACHINES FROM 100 TO 1200 TON

The three Multi-Inject robot models are specially designed for transverse unloading in the mold without touching the secondary vertical injection unit of the IMM.

Unlike conventional Cartesian robots, these robots are designed with a demolding arm that slides on the horizontal axis to access the mold vertically.

They are more economic than a side-entry robot and also benefit from the flexibility of a 3-axis Cartesian robot.

| MULTI-INJECT 20 | MULTI-INJECT 30 | MULTI-INJECT 40



08/2024 - MI/ CN - Non contractual document. The technical specifications and performances are given for information purposes only and for each standard robot configuration. As our products evolve constantly, certain illustrations and information may be modified without prior notice. SEPRO ROBOTIQUE - SAS - RCS La Roche-Sur-Yon n° 399 308 428

MULTI-INJECT

3-AXIS ROBOTS

MULTI-INJECT 20 | MULTI-INJECT 30 | MULTI-INJECT 40

SPECIFICATIONS

MI-20	MI-30	MI-40
Mold clamping force (T - Metric Tons)		
100 - 250	200 - 500	400 - 1200
Horizontal stroke (mm) - Can be adapted by 500 mm steps		
2000 - 5000	2500 - 5000	2500 - 6000
Demold stroke - Transver	-	
700	900	1200
Vertical stroke (mm) - Dir		
1400	-	-
Vertical stroke (mm) - Te		
-	1800	2500
Maximum load (parts + E	, , =,	00
10	15	30
R1 pneumatic rotation (0-	-90°) ✓	,
Part grip - Vacuum up to	٧	✓
8	8	8
Part-grip : Pressure up to	-	O
8	8	8
Compact beam-mounted control cabinet		
✓	√	✓
VISUAL 2 control system		
✓	✓	✓
OPTIONS	0 (0 000 (000)	
Pneumatic rotation R1-R2	2 (0-90°-180°)	/
R1 servo rotation (0-180°	•	٧
111 301 VO 10 (ation (0-100) · 1\2 (0-000)	✓
Visual 3 control system		
\checkmark	✓	✓
ECO Air	,	,
\checkmark	\checkmark	✓